

# Direct modeling of frequency spectra and waveform generation based on phase recovery for DNN-based speech synthesis

Shinji Takaki<sup>1</sup>, Hirokazu Kameoka<sup>2</sup>, Junichi Yamagishi<sup>1</sup>

<sup>1</sup> National Institute of Informatics

<sup>2</sup> NTT Communication Science Laboratories

# Background (1/2)

## Statistical parametric speech synthesis

- DNN-based speech synthesis [Zen et al.; 12]

## Waveform generation for TTS

- High-quality vocoder (STRAIGHT, WORLD)
  - Quality deterioration such as buzziness
- Sinusoidal vocoder [Hu et al.; 15]
- Modeling complex spectra [Hu et al.; 16]
- Signal reshaping [Espic et al.; 16]
- Sample RNN [Mehri et al.; 17]
- WaveNet [van den Oord et al.; 16]

Text-to-speech synthesizer with neither the vocoder and  
computational explosion

# Background (2/2)

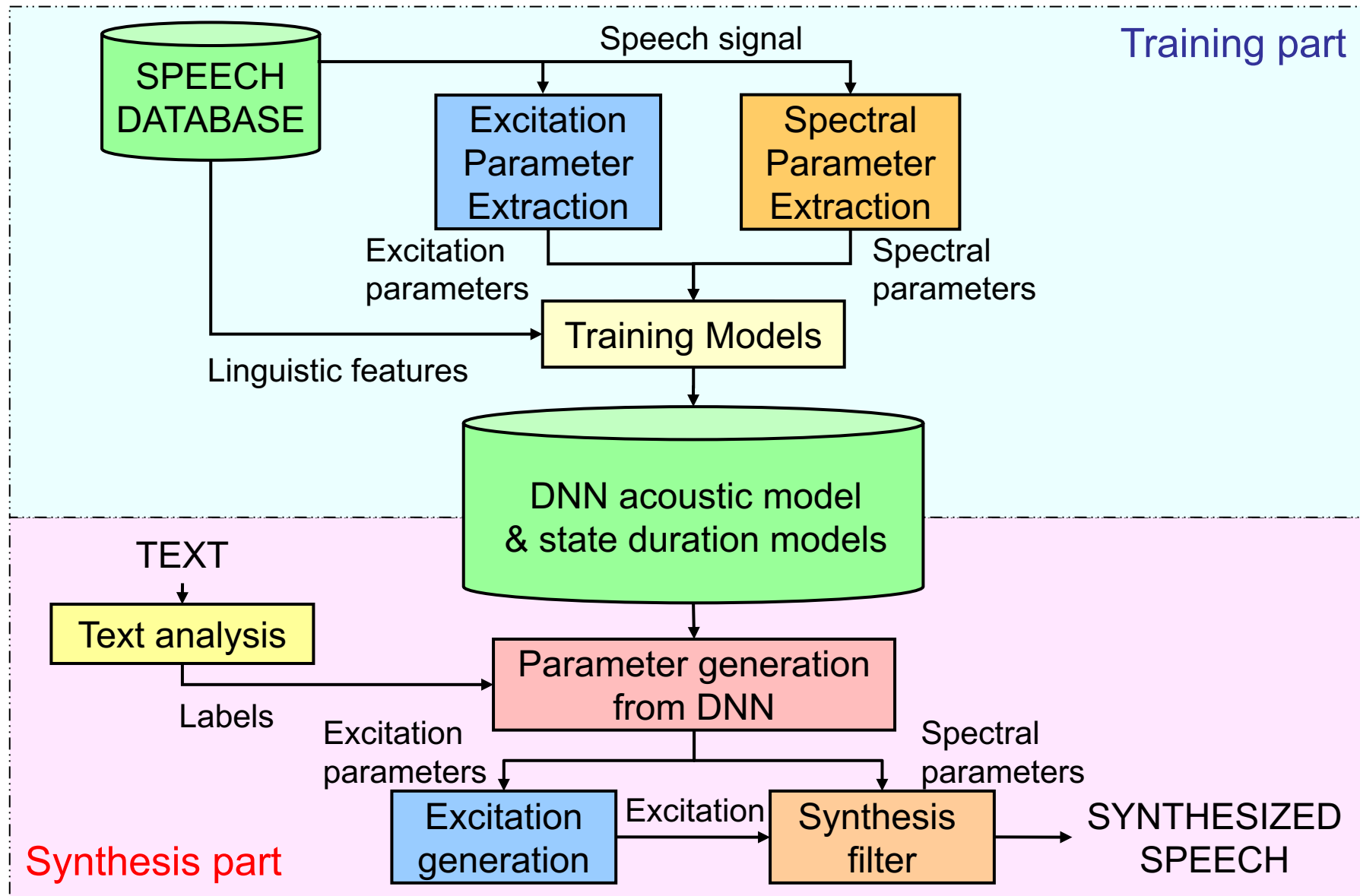
## Direct modeling of frequency spectra

- Simple short-time Fourier transform (STFT)
- Spectral envelopes and harmonic structure are included
- Advantages of using STFT
  - The representation is much closer to original waveform
  - DNNs need to be used per frame instead of per sample
- Waveform generation based on phase recovery

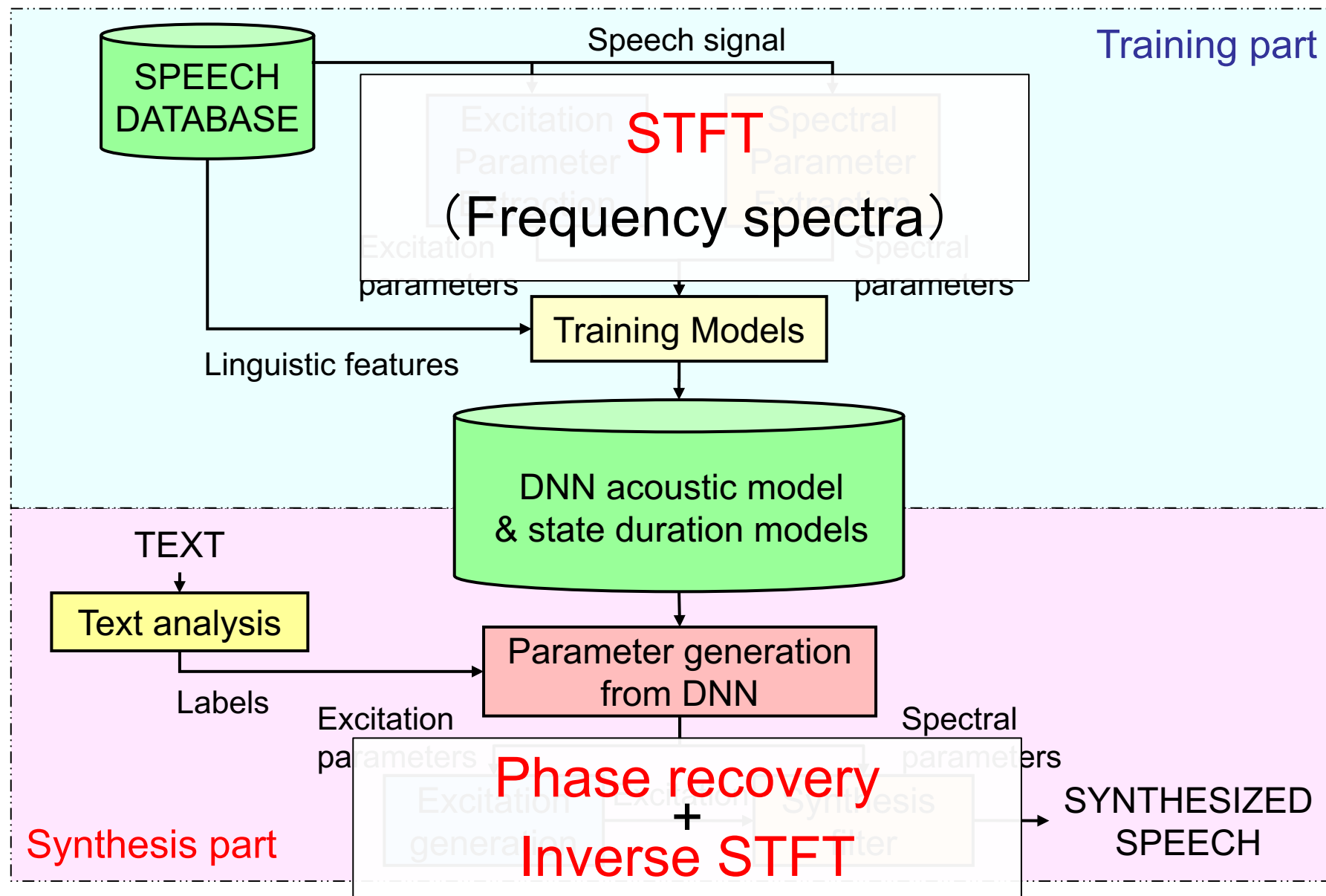
## Prediction of STFT based on a DNN

1. The use of F0 information as well as linguistic feature
2. KLD-based objective criterion
3. Post-filtering of predicted STFT

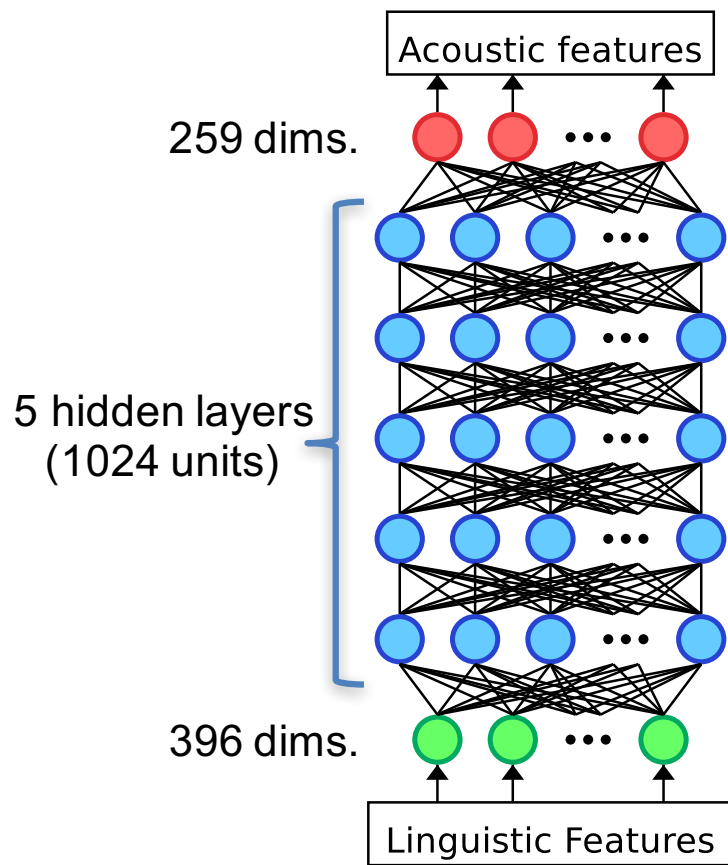
# Statistical parametric speech synthesis



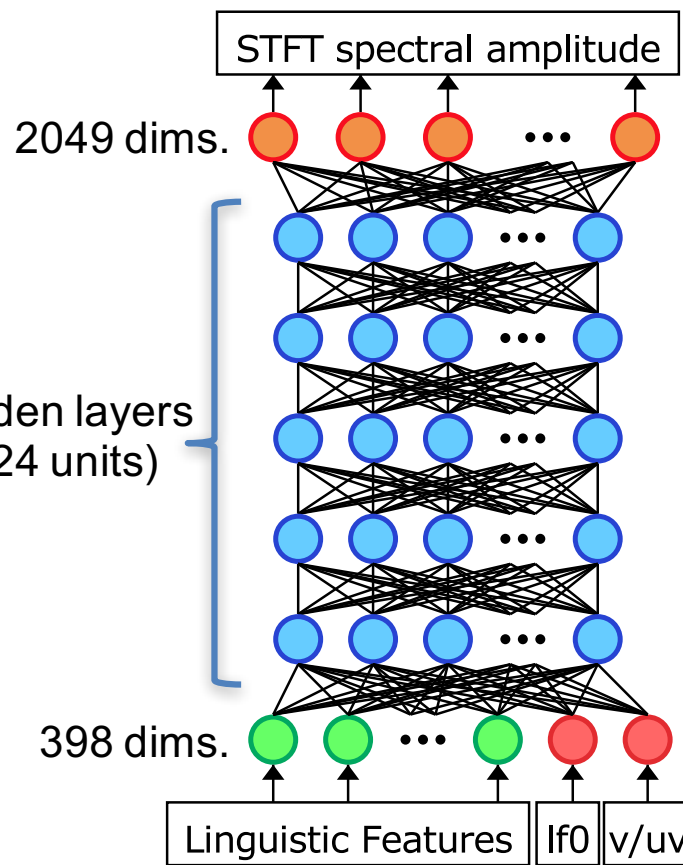
# Statistical parametric speech synthesis



# Architectures (Left conventional, Right proposed)



Vocoder-based  
conventional framework



STFT-based  
proposed framework

F0 information is explicitly used as inputs  
STFT spectral amplitudes are the outputs

# KLD-based training

## Least square error (LSE)

$$E_{SE} = \frac{1}{2} \sum_{t=1}^T \sum_{d=1}^D (o_{t,d} - y_{t,d})^2$$

$o_{t,d}$ : obs.,  $y_{t,d}$ : DNN output,  $t$ : frame index,  $d$ : dim.

## Kullback-Leibler divergence (KLD)

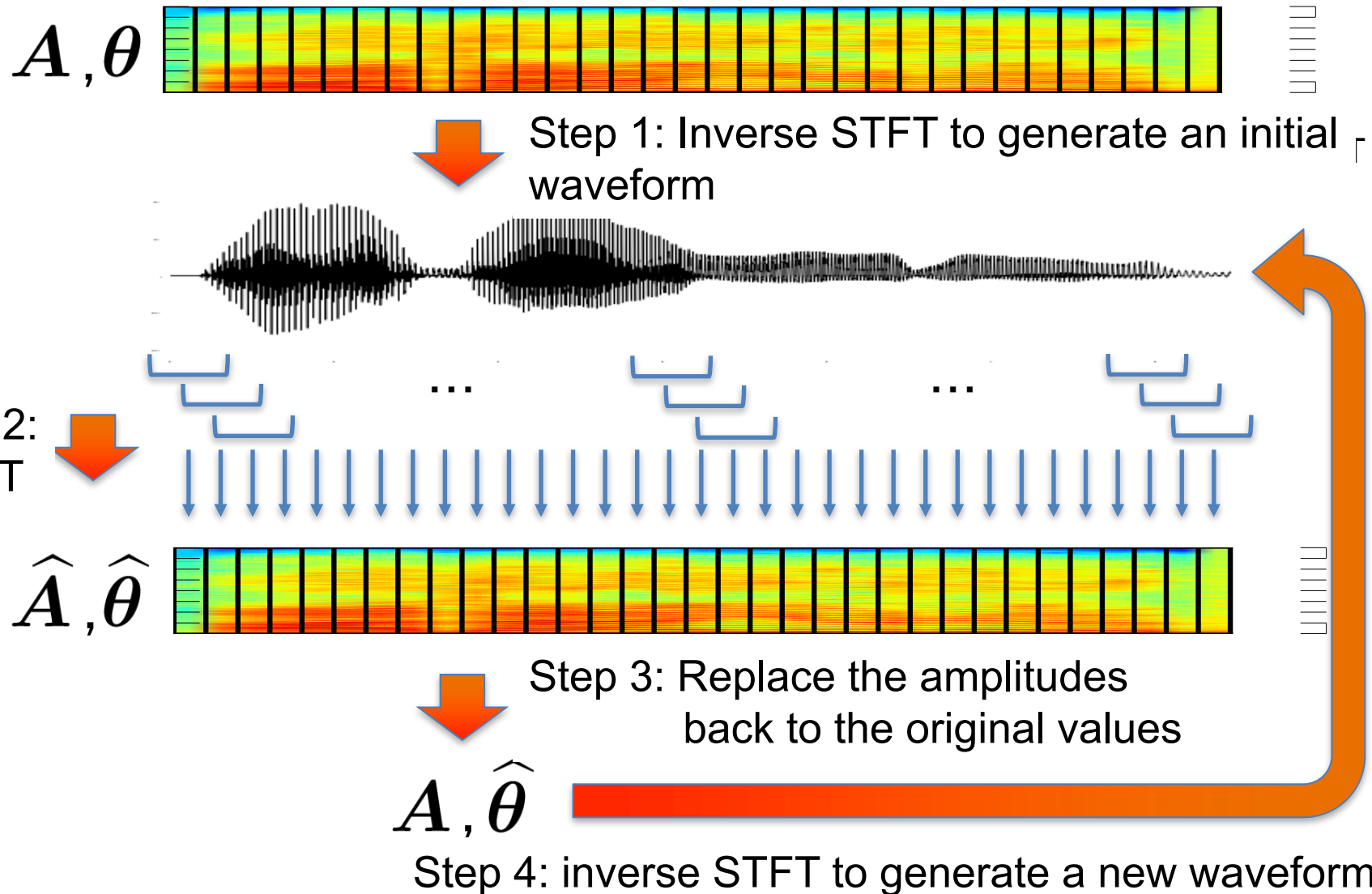
- KLD-based criterion has been successfully used for spectral-domain source separation with NMF
- The sigmoid is used for an output layer in this work

$$E_{KL} = \sum_{t=1}^T \sum_{d=1}^D o_{t,d} \log \frac{o_{t,d}}{\tilde{y}_{t,d}} - o_{t,d} + \tilde{y}_{t,d}, \quad \tilde{y}_{t,d} = s_d y_{t,d} + b_d$$

$o_{t,d}$ : linear spectrum,  $s_d, b_d$ : fixed values for unnormalization

# Phase recovery from STFT amplitudes

Iterative framework to refine phase [Griffin and Lim; 84]





# Experimental conditions (1/2)

Database	Blizzard Challenge 2011 Professional female, 12,085 utterances (17 hours)
Sampling frequency	48 kHz / 32 kHz
FFT points	4096 (2049-dim) / 2048 (1025-dim)
Feature vector (Conventional system)	59 mel-cepstrum $+\Delta + \Delta^2$ log F0 $+\Delta + \Delta^2$ Voiced/unvoiced parameter 25-band aperiodicity $+\Delta + \Delta^2$

## Detailed information of the proposed system

- Training:  $f_0$ , v/uv obtained from natural speech
- Synthesis:  $f_0$ , v/uv synthesized from Baseline
- 100 iteration for phase recovery

# Experimental conditions (2/2)

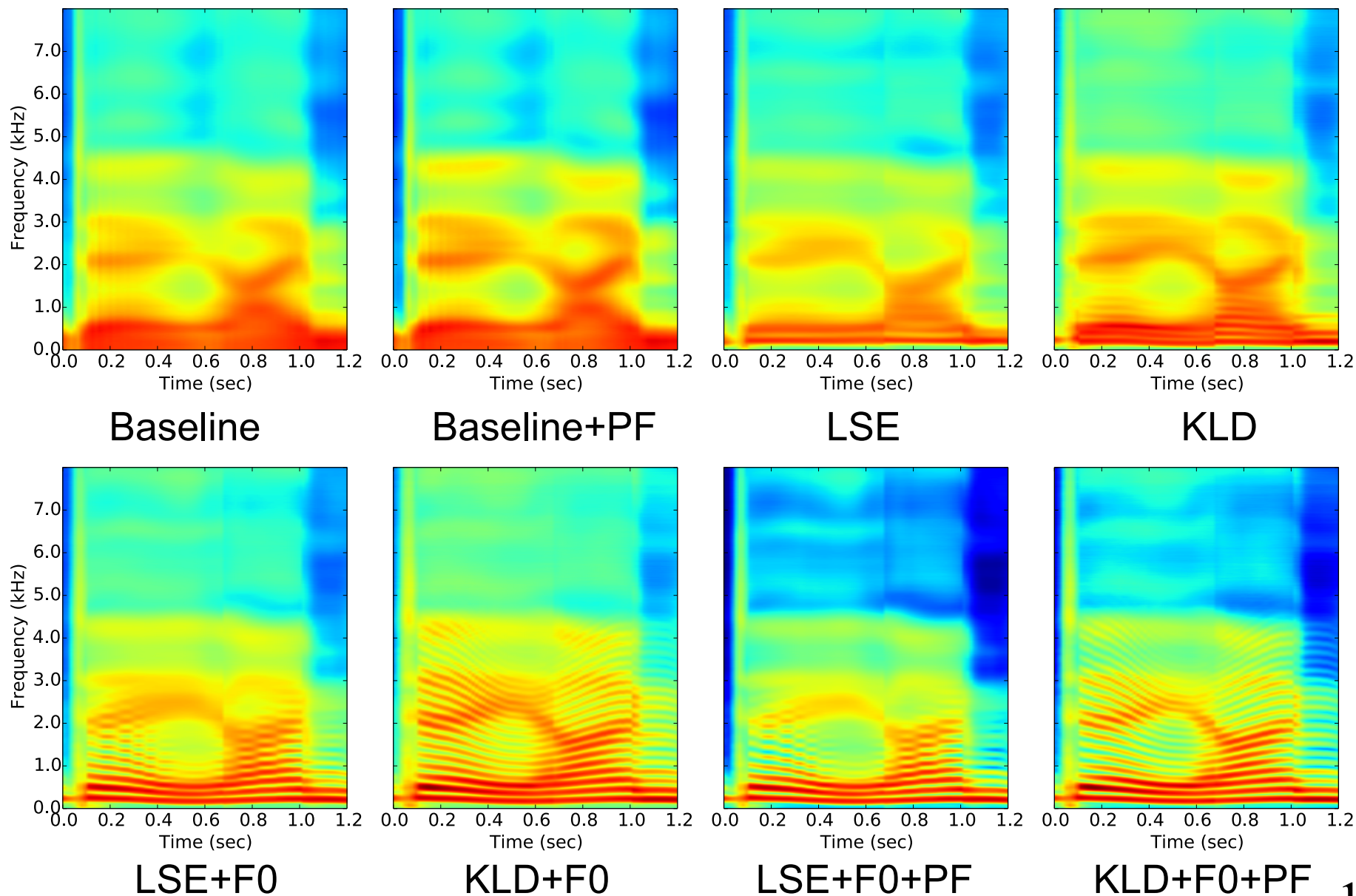
System name	Input	Output	Criterion	Post-filter	Generation
Baseline	Text	Vocoder para.	LSE		Vocoder
Baseline+PF	Text	Vocoder para.	LSE	✓	Vocoder
LSE	Text	log STFT	LSE		Phase recovery
KLD	Text	STFT	KLD		Phase recovery
LSE+F0	Text, F0	log STFT	LSE		Phase recovery
KLD+F0	Text, F0	STFT	KLD		Phase recovery
LSE+F0+PF	Text, F0	log STFT	LSE	✓	Phase recovery
KLD+F0+PF	Text, F0	STFT	KLD	✓	Phase recovery

## Signal processing post-filter for peak enhancement

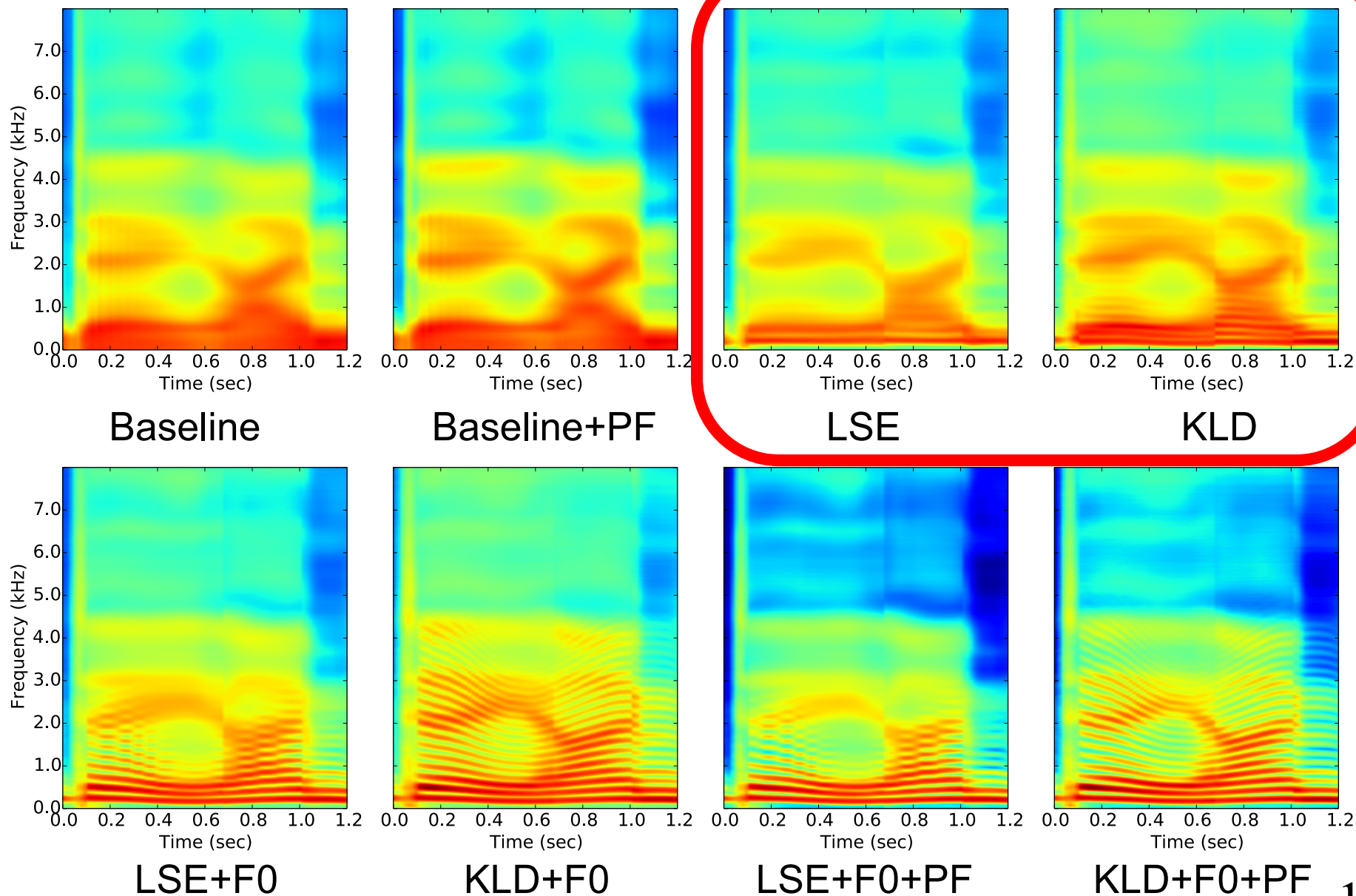
1. Predicted STFT are converted into linear-scale cepstrum
2. The post-filter is applied to the cepstrum
3. The post-filtered cepstrum is converted back into STFT

Wed-P-8-4-6 : GAN-based post-filter for STFT

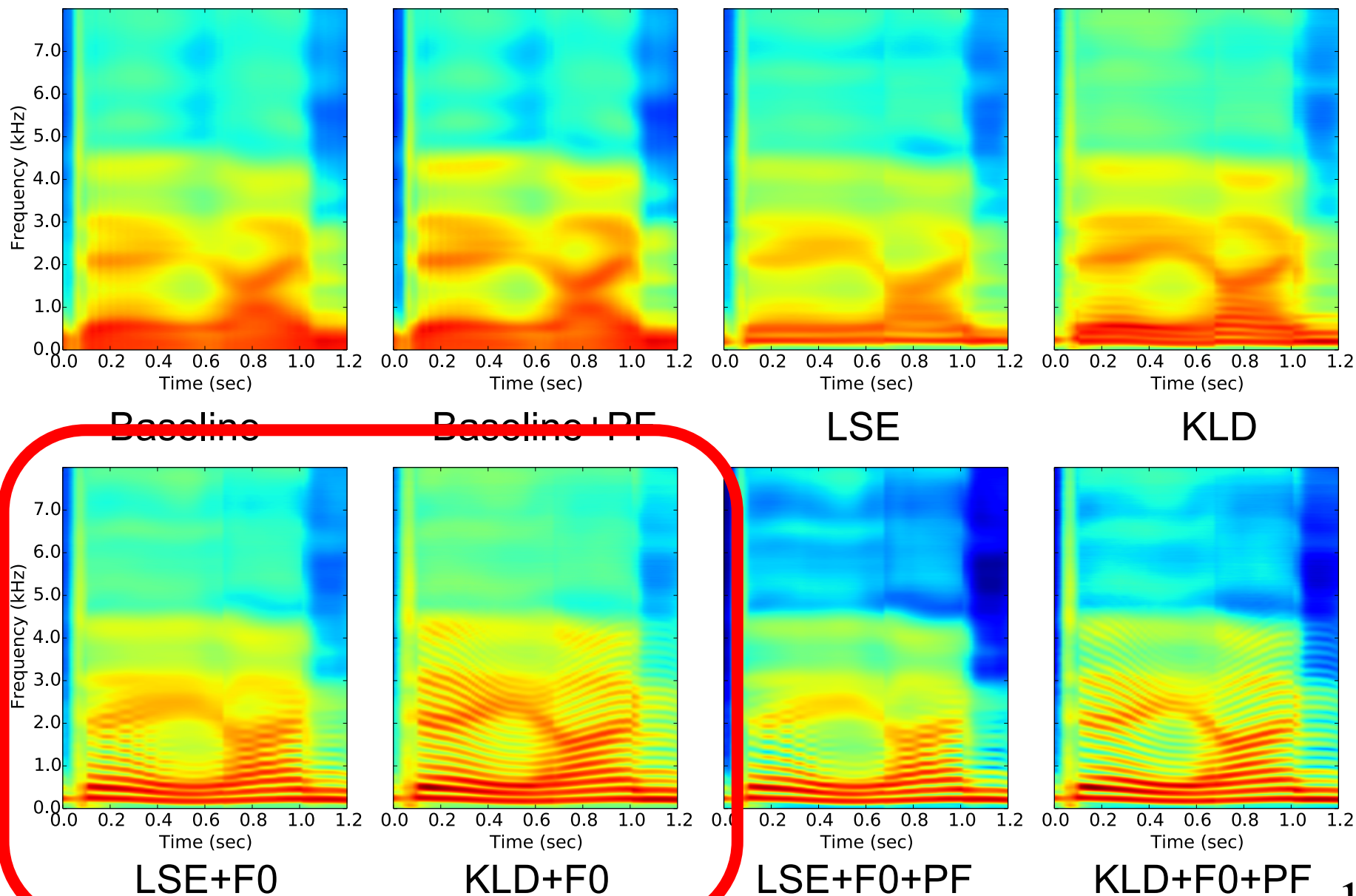
# Synthetic spectra (Low-frequency parts)



# Synthetic spectra (Low-frequency parts)

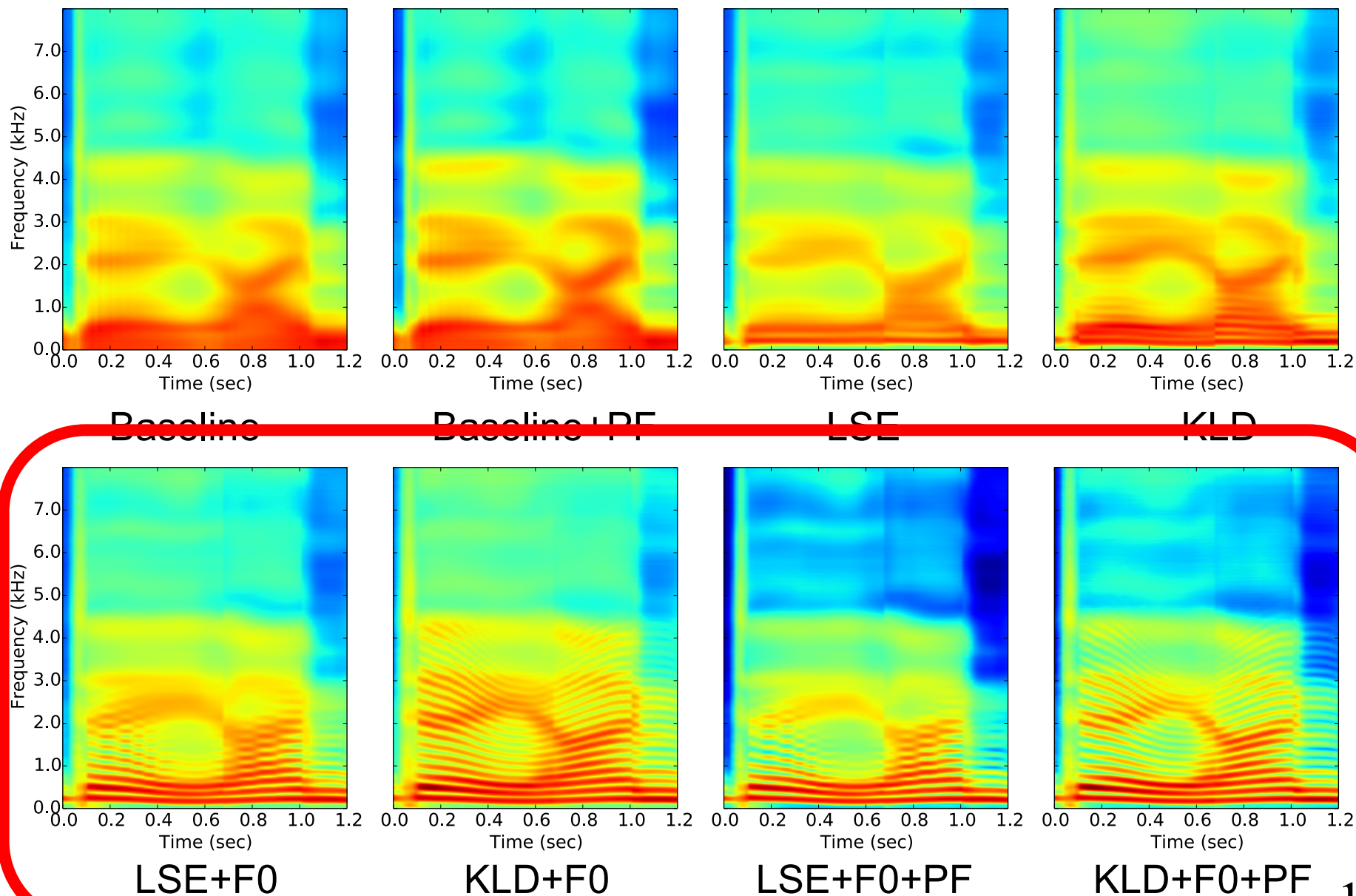


# Synthetic spectra (Low-frequency parts)

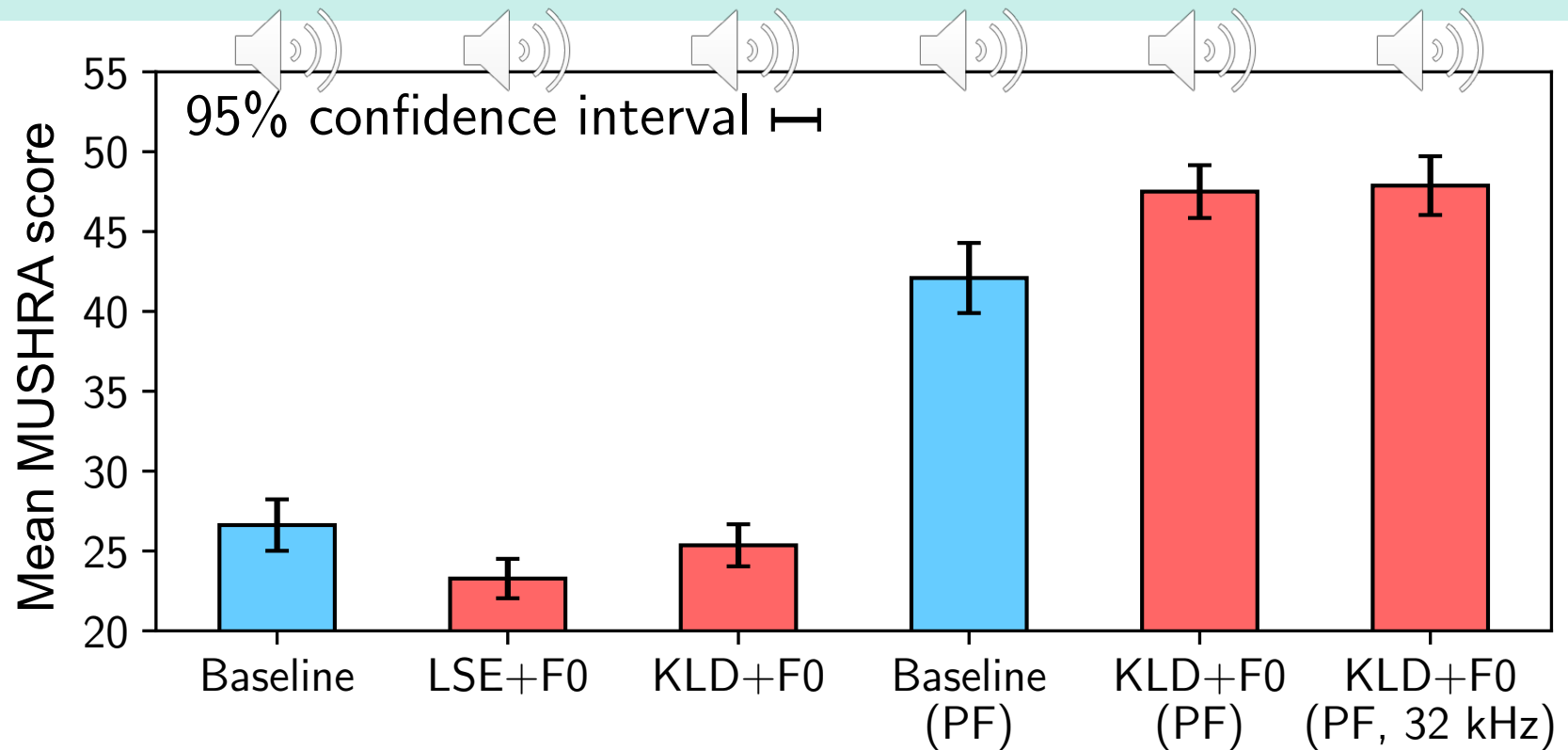




# Synthetic spectra (Low-frequency parts)

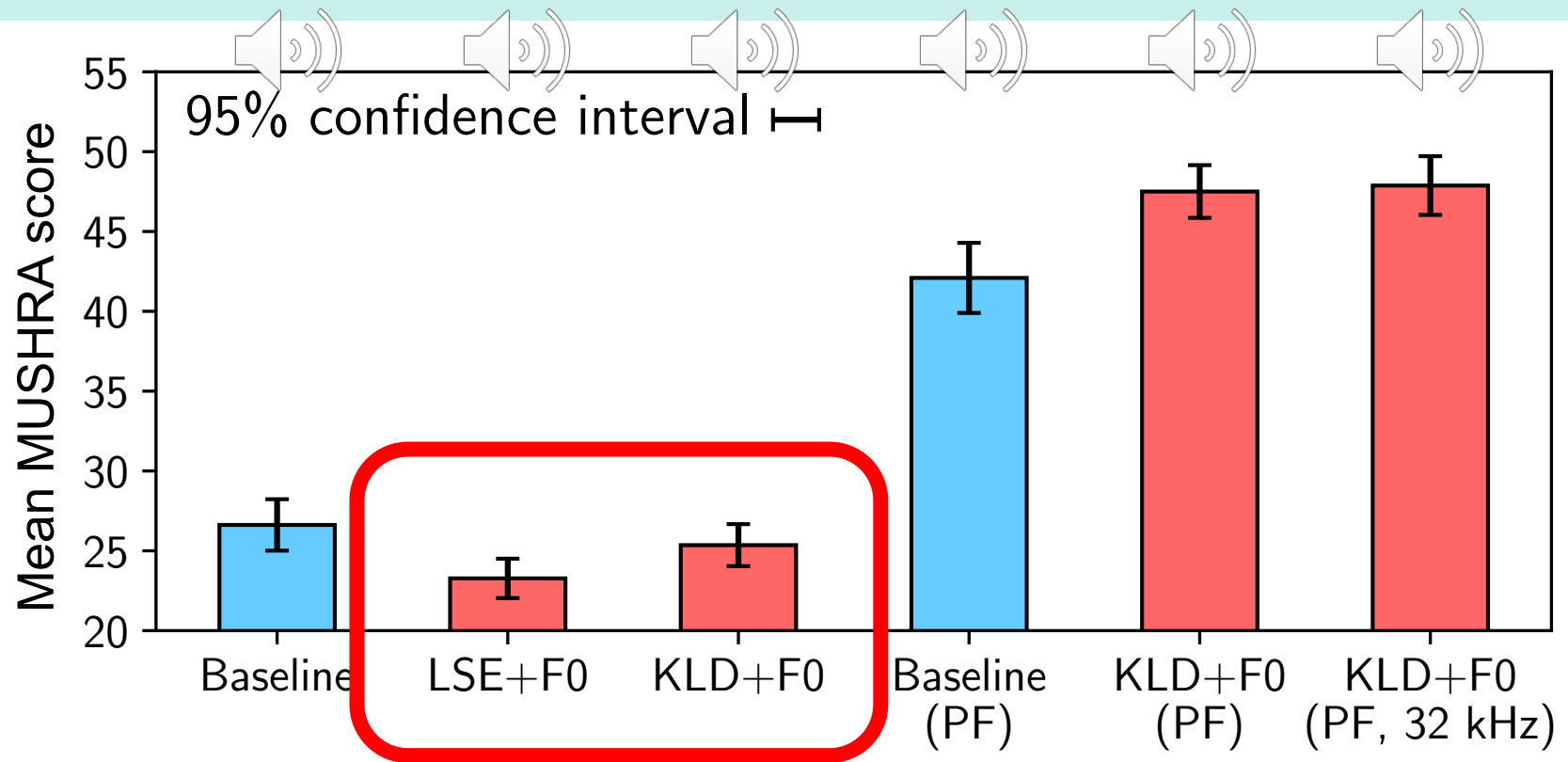


# Subjective test (MUSHRA, 14 native participants)



- KLD-based criterion was more appropriate
- Performance of STFT-based systems without post-filtering was insufficient
- The proposed systems with post-filtering outperformed the conventional DNN-based synthesizer

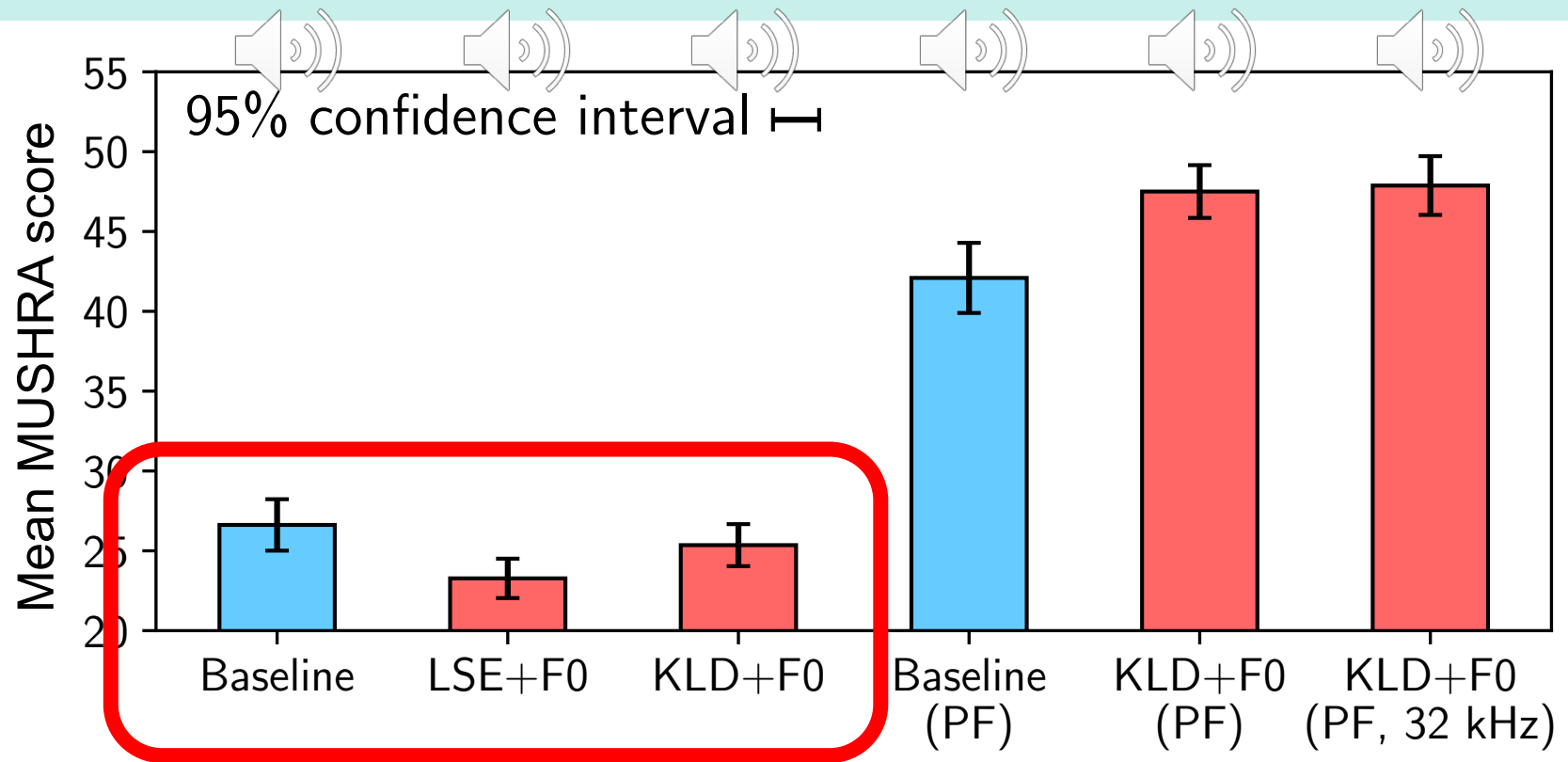
# Subjective test (MUSHRA, 14 native participants)



- KLD-based criterion was more appropriate
- Performance of STFT-based systems without post-filtering was insufficient
- The proposed systems with post-filtering outperformed the conventional DNN-based synthesizer

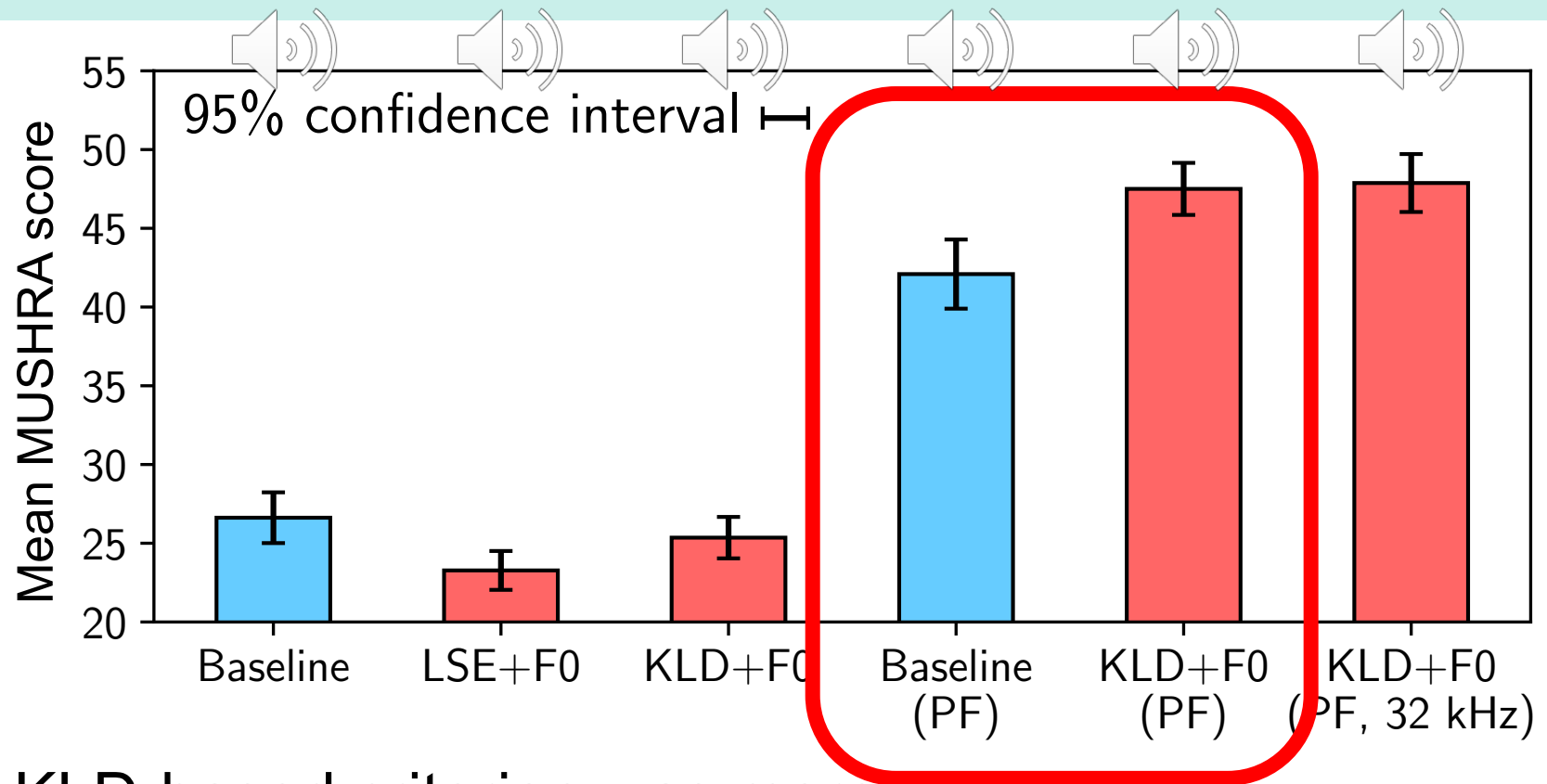


# Subjective test (MUSHRA, 14 native participants)



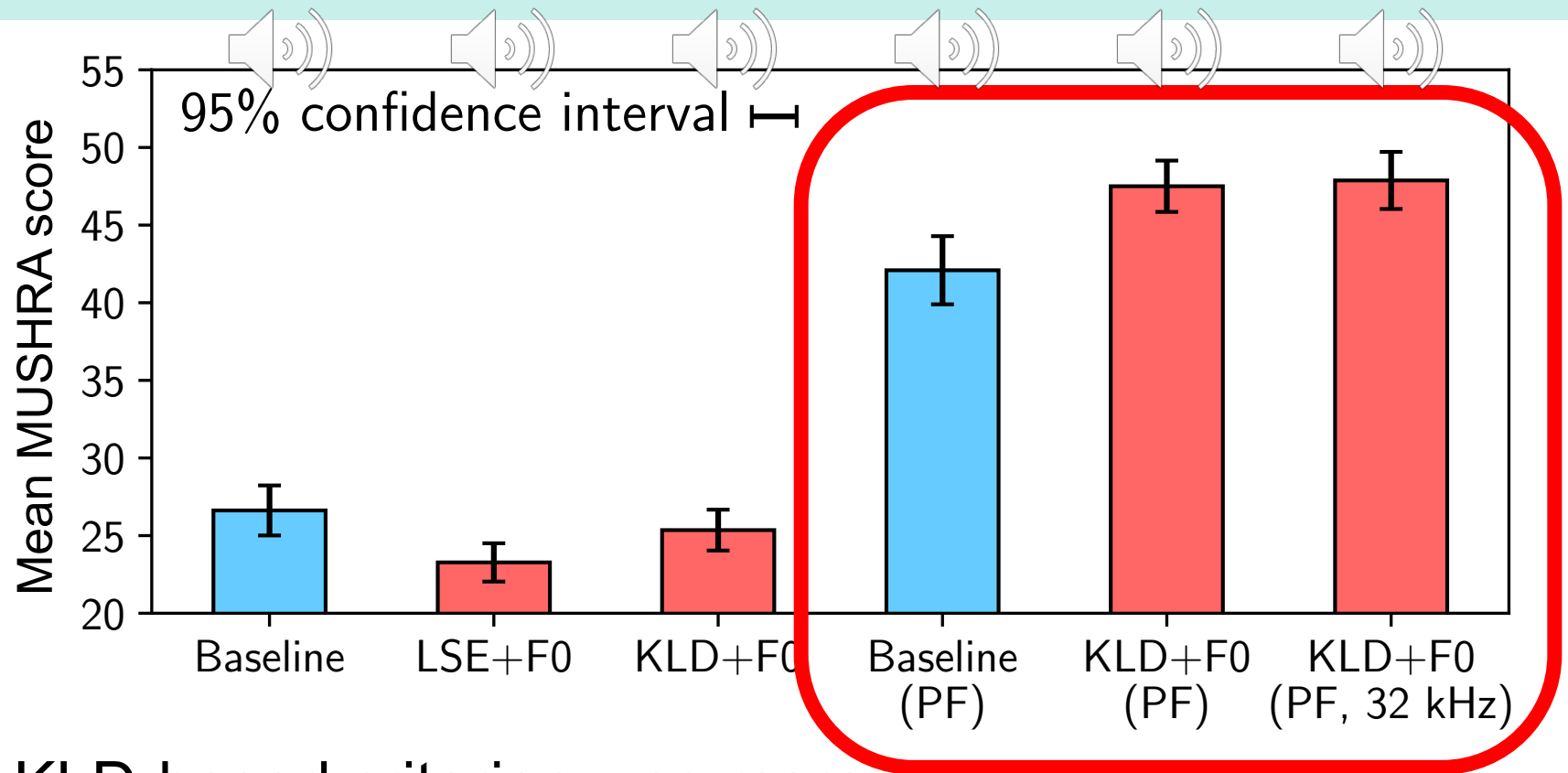
- KLD-based criterion was more appropriate
- Performance of STFT-based systems without post-filtering was insufficient
- The proposed systems with post-filtering outperformed the conventional DNN-based synthesizer

# Subjective test (MUSHRA, 14 native participants)



- KLD-based criterion was more appropriate
- Performance of STFT-based systems without post-filtering was insufficient
- The proposed systems with post-filtering outperformed the conventional DNN-based synthesizer

# Subjective test (MUSHRA, 14 native participants)



- KLD-based criterion was more appropriate
- Performance of STFT-based systems without post-filtering was insufficient
- The proposed systems with post-filtering outperformed the conventional DNN-based synthesizer

# Conclusion

Direct modeling of frequency spectra

Waveform generation based on phase recovery

- These approaches were effective
  1. The use of F0 information as well as linguistic features
  2. KLD-based objective criterion
  3. Post-filtering of predicted STFT

Future work

- Wed-P-8-4-6: GAN-based post-filtering for STFT
- Phase modeling
- STFT-conditioned WaveNet, SampleRNN

# Synthetic samples

Baseline	    
Baseline+PF	    
LSE+F0	    
KLD+F0	    
KLD+F0+PF	    
KLD+F0+PF (32kHz)	    

# Details of KLD

## Kullback-Leibler divergence (KLD)

- Representing parameters of Poisson distribution
  - Mean and variance are same
- Derivative

General

$$E_{KL} = \sum_{d=1}^D o_{t,d} \log \frac{o_{t,d}}{y_{t,d}} - o_{t,d} + y_{t,d},$$

$$\frac{\partial E_{KL}}{\partial y_{t,d}} = 1 - \frac{o_{t,d}}{y_{t,d}},$$

Our work

$$E_{KL} = \sum_{d=1}^D o_{t,d} \log \frac{o_{t,d}}{\tilde{y}_{t,d}} - o_{t,d} + \tilde{y}_{t,d},$$

$$= \sum_{d=1}^D o_{t,d} \log \frac{o_{t,d}}{s_d y_{t,d} + b_d} - o_{t,d} + s_d y_{t,d} + b_d,$$

$$\frac{\partial E_{KL}}{\partial y_{t,d}} = s_d \left( 1 - \frac{o_{t,d}}{s_d y_{t,d} + b_d} \right),$$